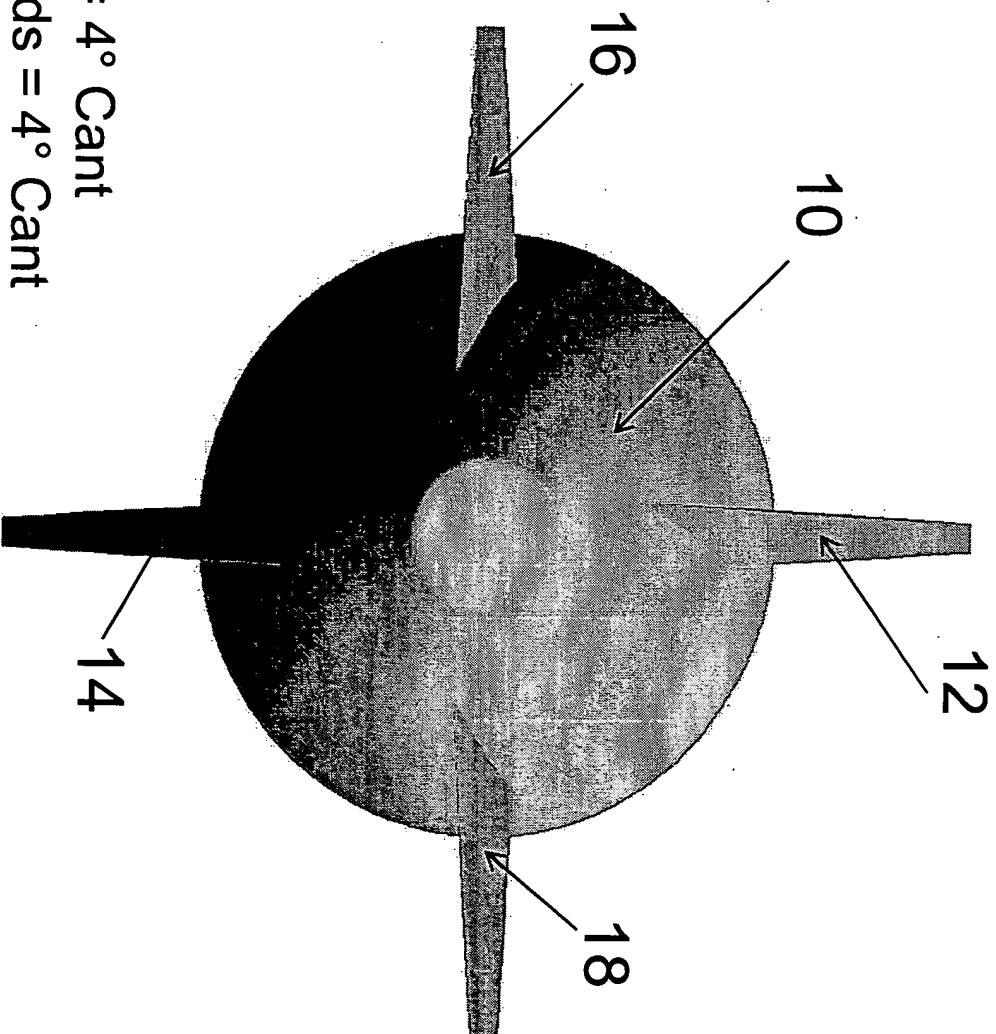


# Figure 1 – Front View



Spin Canards =  $4^\circ$  Cant  
Steering Canards =  $4^\circ$  Cant

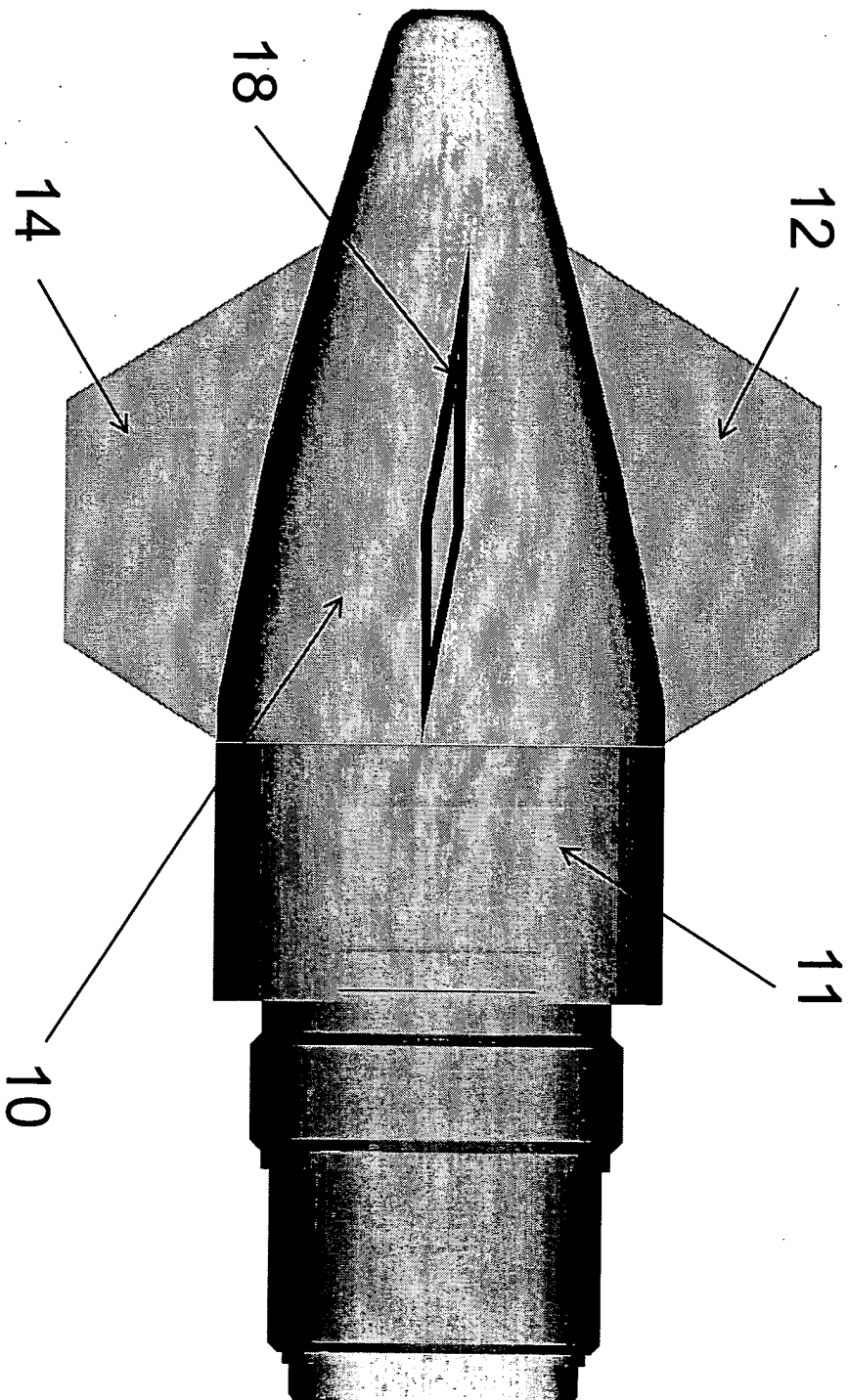
Fig. 1

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**Figure 2 – Side View**



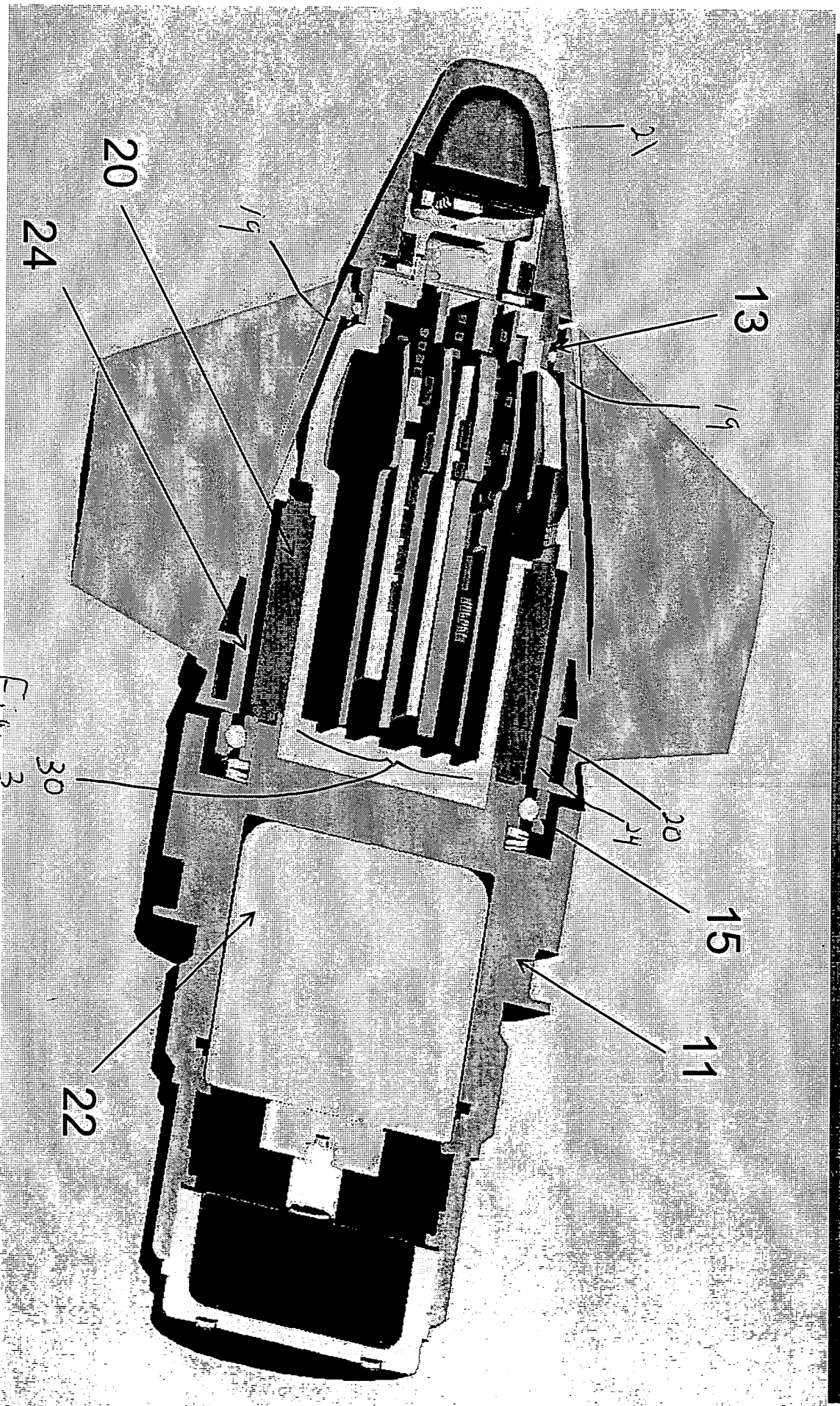
*Fig. 2*

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Figure 3 – Cross-Section View



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